

APPLICATION OF HOMOTOPY PERTURBATION METHOD ON OSCILLATOR OF COMPLEX VARIABLE

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ABSTRACT

In this work a nearly new established analytical approach, He's homotopy-perturbation method (HPM) has been applied to solve the differential equation of oscillator with a high degree of nonlinearity. The objective of this paper is to present an analytical investigation to analyze the vibration cubic positive nonlinearity of complex variable in nonlinear dynamic systems. The comparison of the solution obtained by HPM has are done against the numerical solution in confirmation of the applicability of the method and its effectiveness in solving problems with high degree of nonlinearity.

Keywords: *Homotopy -Perturbation method, Runge-Kutta method, Parametrically excited oscillator.*

1. INTRODUCTION

Nonlinear phenomena are of fundamental importance in various fields of science and engineering. Most nonlinear models of real-life problems are still very difficult to solve, either numerically or theoretically. Many assumptions have to be made unnecessarily to make nonlinear models solvable. One particularly interesting aspect of the physical behavior of microelectromechanical and nanoelectromechanical systems (MEMS) and (NEMS) is their nonlinear mechanical response at relatively small deviations from equilibrium. Since there are some limitations in using the common perturbation method together with the fact that this method is based on the existence of small parameter, developing the method for different applications is very difficult. Therefore, a number of semi analytical methods, including the homotopy-perturbation method (HPM), proposed by He [1-18], and the variational iteration method [19-20] have recently been developed by using new techniques to eliminate the small parameter.

It is important to investigate the dynamic behavior of these systems. Vibrations of such systems occur in wide range of mechanics, due to time-varying loads, especially periodic ones. The motivation of this paper is to extend the homotopy perturbation method (HPM) proposed oscillator of Complex Variable

In the present work, the HPM method is applied on the governing equation of Mathieu-Duffing system and the results are compared with that of the numerical method to demonstrate the effectiveness of the approach. The governing equation of Mathieu-Duffing system which is considered in this study is described by the following high-order nonlinear differential equation:

$$\ddot{\varphi} + \gamma \dot{\varphi} + [\xi + 2\varepsilon \cos(2t)]\varphi + \beta \varphi^3 = F_0 \sin 2t \quad (1)$$

where dots indicate differentiation with respect to the time (t), $\varepsilon \ll 1$ is a small parameter, β is the parameter of nonlinearity, and ξ is the transient curve .

The initial condition considered in this study is defined by $\varphi = 1, \dot{\varphi} = 0$.

2. THE BASIC CONCEPT OF HPM

consider the following equation:

$$A(x) - f(r) = 0 \quad r \in \Omega \quad (2)$$

with the boundary condition of:

$$B\left(x, \frac{\partial x}{\partial t}\right) = 0 \quad r \in \Gamma \quad (3)$$

where A is a general differential operator, B a boundary operator, $f(r)$ a known analytical function and Γ is the boundary of the domain Ω . A can be divided into two parts of L and N , where L is linear and N is nonlinear. Eq. (2.1) can therefore be rewritten as follows:

$$L(x) + N(x) - f(r) = 0 \quad r \in \Omega \quad (4)$$

Homotopy perturbation structure is shown as follows:

$$H(v, p) = (1-p)[L(v) - L(x_0)] + p[A(v) - f(r)] = 0 \quad (5)$$

where,

$$v(r, p): \Omega \times [0,1] \rightarrow R \tag{6}$$

In Eq. (2.4), $p \in [0, 1]$ is an embedding parameter and x_0 is the first approximation that satisfies the boundary condition. We can assume that the solution of Eq. (2) can be written as a power series in p , as following:

$$v = v_0 + p v_1 + p^2 v_2 + \dots = \sum_{i=0}^n v_i p^i \tag{7}$$

and the best approximation for the solution is:

$$x = \lim_{p \rightarrow 1} v = v_0 + v_1 + v_2 + \dots \tag{8}$$

3. APPLICATION OF HPM

applying the HPM on the nonlinear equation of (1),

$$(1 - p) (\ddot{\varphi} + \gamma \dot{\varphi} + \xi \varphi) + p (\ddot{\varphi} + \gamma \dot{\varphi} + [\xi + 2\varepsilon \cos(2t)]\varphi + \beta \varphi^3 - F_0 \sin 2t) = 0 \tag{9}$$

expanding the equation and collecting based on the coefficients of p -terms:

$$\begin{cases} p^0 : \ddot{\varphi}_0 + c\dot{\varphi}_0 + k_1\varphi_0 = 0 \\ p^1 : \ddot{\varphi}_1 + \gamma \dot{\varphi}_1 + \xi_1\varphi_1 - 2\varepsilon\varphi_0 + \beta\varphi_0^3 + 4\varepsilon \cos(t)^2\varphi_0 - F_0 \sin(2t) = 0 \\ p^2 : \ddot{\varphi}_2 + \gamma\dot{\varphi}_2 + \xi\varphi_2 - 2\varepsilon\varphi_1 + 4\varepsilon \cos(t)^2\varphi_1 + 3\beta\varphi_0\varphi_1^2 = 0 \\ p^3 : \dots \end{cases} \tag{10}$$

One can now try to obtain the solution of different iterations (3.2), in the form of:

$$\varphi_0(t) = \frac{1}{2} \frac{(\gamma + \sqrt{\gamma^2 - 4\xi})e^{(-\frac{1}{2}\gamma + \frac{1}{2}\sqrt{\gamma^2 - 4\xi})t}}{\sqrt{\gamma^2 - 4\xi}} - \frac{1}{2} \frac{(\gamma - \sqrt{\gamma^2 - 4\xi})e^{(-\frac{1}{2}\gamma - \frac{1}{2}\sqrt{\gamma^2 - 4\xi})t}}{\sqrt{\gamma^2 - 4\xi}} \tag{11}$$

The obtained iteration is used to generate the equation for the next iteration, and therefore the second and third iterations are obtained.

4. RESULTS AND DISCUSSIONS

The results of the HPM solution are tabulated in Table 1. Also to demonstrate the effectiveness of the proposed method, HPM, the results are also pictured in figures. From the figures, Figure1 through 3, it's obvious that HPM is powerful in finding analytical solutions for a wide class of nonlinear problems. These figures show obviously the excellent agreement between HPM and numerical solution.

Table 1. A comparative table for error detection of the analytic method, for $\gamma = 3, \xi = 2.01, \varepsilon = 0.01, \beta = 2, F_0 = 1$.

t	x		x'	
	HPM	RK	HPM	RKf45
0	1	1	0.00	0.00
1	0.4544060072	0.505374334790630874	-0.3695403461	-0.303432300570351254
2	0.2039961695	0.257540517444629858	-0.3068046675	-0.340792164974021261
3	-0.1254177687	-0.100146714434942219	-0.1981001184	-0.218168996091851976
4	-0.02917428662	-0.0173018074459907502	0.3111043130	0.301619978381819809
5	0.1519734217	0.156520938641227126	-0.0788630729	-0.0846998347044815026
6	-0.1004193148	-0.0993175983679624314	-0.2447736236	-0.245921904022073950
7	-0.07004090632	-0.0680631878741948804	0.2840196936	0.284616101932424870
8	0.1580626315	0.159265518808038852	0.0089960259	0.00719991014298755182
9	-0.06177042964	-0.0619039606809274820	-0.2912643749	-0.291523322750080804
10	-0.1067465441	-0.105412445157567314	0.2335204042	0.235326410676588772

The results shown in table 1 indicates that the HPM experiences a high accuracy. In addition, in comparison with RK method and other analytical methods, a considerable reduction of the volume of the calculation can be seen in HPM. It can be approved that HPM is powerful in finding analytical solutions for a wide class of nonlinear problems. These figures show obviously the excellent agreement between HPM and RK method.

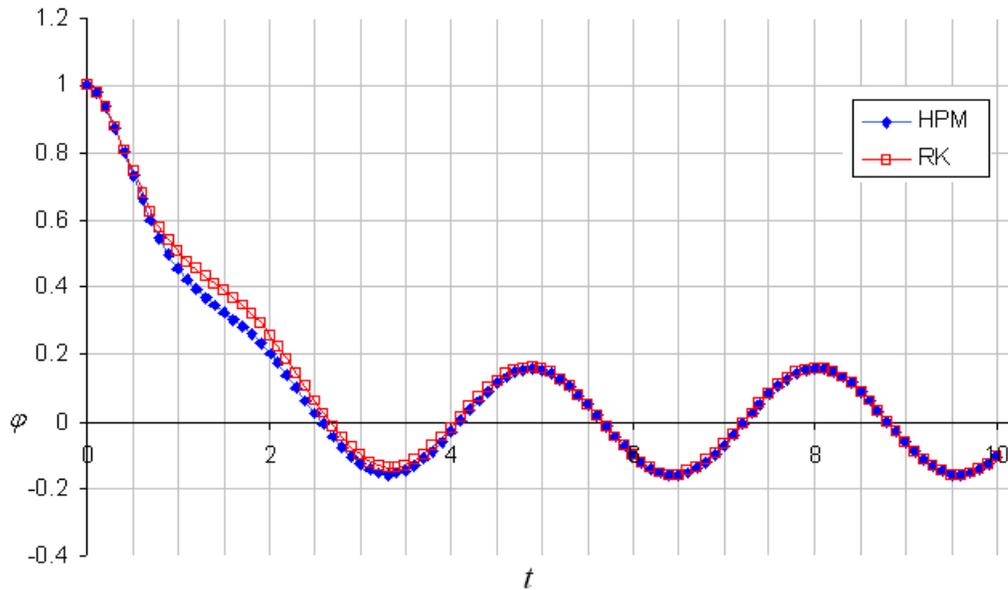


Figure (1): comparison of HPM and RK.Displacement φ based on time t

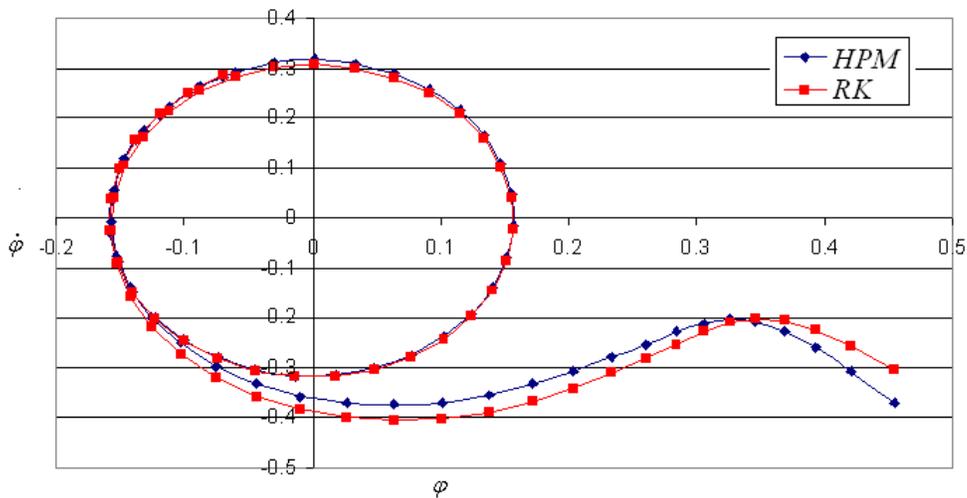


Figure (2): comparison of HPM and RK for Velocity $\dot{\varphi}$ based on displacement φ .

5. CONCLUSIONS

In this work, the HPM has been employed to analyze of parametrically excited oscillator with strong cubic positive nonlinearity of Complex Variable in Nonlinear Dynamic Systems with Forcing. The results obtained from this method have been compared with those obtained from numerical method using RK algorithm. This comparison shows excellent agreement between the two methods. Also, HPM does not require small parameters, so the limitation of the conventional perturbation method could be eliminated.

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